Desarrollo de inteligencia ambiental con SociAAL

Pablo Campillo-Sanchez, Jorge J. Gómez-Sanz

{pabcampi,jjgomez,jpavon}@ucm.es Universidad Complutense de Madrid

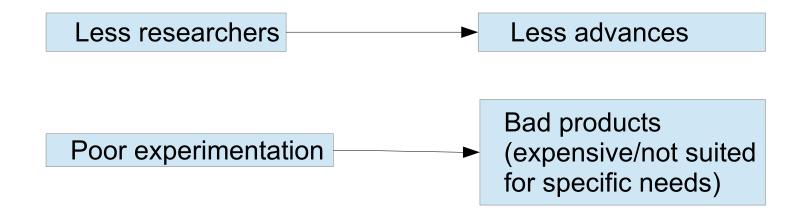
TIN2011-28335-C02-01. http://grasia.fdi.ucm.es/sociaal





Introduction

- Model driven solution for supporting Ambient Assisted Living development (AAL)
- AAL is expensive: equipment, human resources, time





What a AAL development may look like

 First of all, develop an application that detects when one person falls (videos from LTU CS)

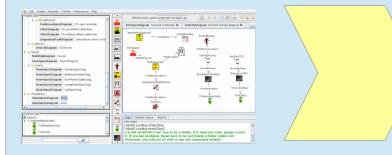


- Once developed, it's testing time
 - It can be dangerous
 - You cannot repeat the experiment in the same way



Virtual Living Lab: Elements

SociAALML : Scenarios, actors PHAT: 3D Rendering







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Virtual Living Lab: Elements

Model Driven Based: Visual Language + Code generation

SociAALML : Scenarios, actors PHAT: 3D Rendering Diagram PD Low Pffects definition substoroff jALI: Aml Devices 0000 Channel1 e 💮 e 0 0 0 1 2 3 4 5 6 Prog11(Ads)





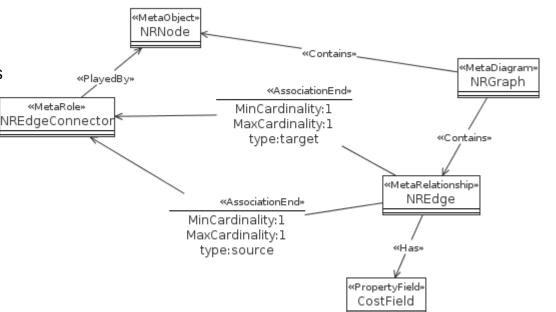
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A custom solution based on open source meta-modeling solution: INGENME

- Goal: quick abstract+concrete grammar for visual languages
 - GOPRR based
 - Couples notation with the grammar
 - First class representation for diagrams & relationship
 - Produces a visual editor + parser: both maven artifacts
 - Share your editor, let others try it!!
- Template in github
 - https://github.com/Grasia/template-ingenme
- Not made to be a replacement to EMF but to cope with a simpler alternative
 - Transition to EMF is possible
- Different applications: SelfMML, INGENIAS, SociAAL
- GPL v3

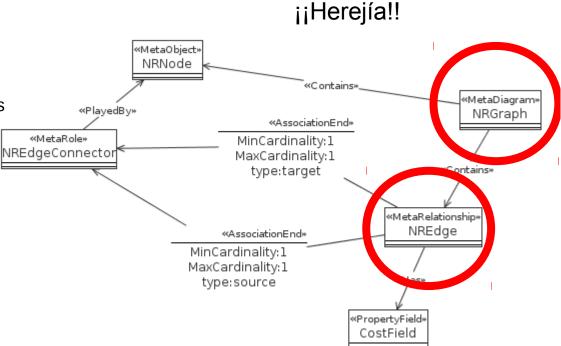
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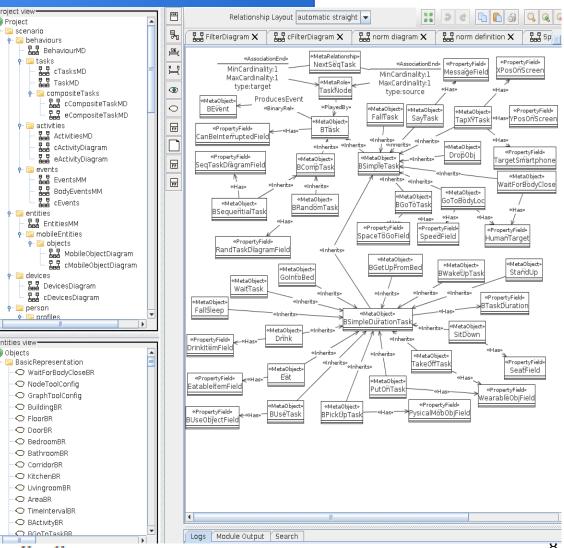


¡¡Peligro!!

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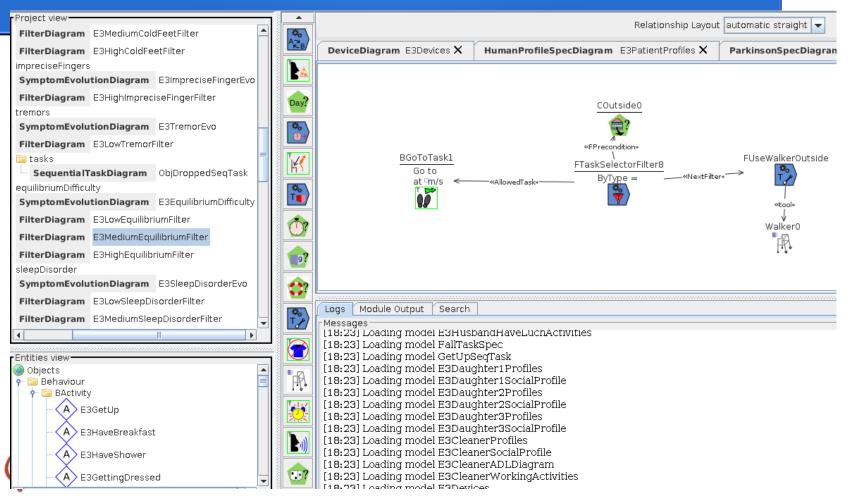
SociAALML

- 190 classes
- 55 relationships
- Need to assess their utility
- Its development driven by use cases
 - Interviews with Parkinson Patients
 - Implementation of the situations



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Produced Editor



Coding

- Using 9 INGENME templates
 - Actor behavior
 - Scenario configuration
 - Norm definition
- Information extraction and template instantation are made through INGENME utilities

@@@program xmlns:xsi="http://www.w3.org/2000/10/XMLSchema-instance"@@@@ @@@repeat id="diseaseProfile"@@@ @@@saveto@@@ @@@file overwrite="yes"@@@ @@@v@@@output@@@/v@@@/phat/agents/filters/@@@v@@@dpName@@@/v@@@ <mark>@@@v@@@actorname@@@/v@@@</mark>.java<mark>@@@/file@@@</mark> @@@text@@@ package phat.agents.filters; public class @@@v@@@dpName@@@/v@@@_@@@v@@@actorname@@@/v@@@ extends DiseaseManager { public @@@v@@@dpName@@@/v@@@_@@@v@@@actorname@@@/v@@@(Agent agent, String simulation) { super(agent); initSymptoms(simulation); ... @@@/text@@@ @@@/saveto@@@ @@@/repeat@@@ @@@/program@@@

Lessons: languages evolve

- The language has to be easily modifiable
- Modifications come from
 - Unsuitability to express some concerns
 - Additional information required from the model-to-code transformation
 - Ease of use
- Current SociAALML comes from several iterations
 - Old examples can still be loaded

pablo@pablo-Latitude-E6540: ~/ucm/sociAAL/code/phat-projects/paams-filters pablo@pablo-Latitude-E... × pablo@pablo-Latitude-E... × pablo@pablo-Latitude-E... × pablo@pablo-Latitude-E... jun 03, 2014 12:10:01 AM com.jme3.bullet.PhysicsSpace removeRigidBody DVERTENCIA: RigidBody com.jme3.bullet.control.RigidBodyControl@faf2105 does not exist in PhysicsS pace, cannot remove. jun 03, 2014 12:10:01 AM com.jme3.bullet.PhysicsSpace removeRigidBody ADVERTENCIA: RigidBody com.jme3.bullet.control.RigidBodyControl@eaadecb does not exist in PhysicsS ace, cannot remove. jun 03, 2014 12:10:01 AM com.jme3.bullet.PhysicsSpace removeRigidBody ADVERTENCIA: RigidBody com.ime3.bullet.control.RigidBodyControl@32012919 does not exist in Physics Space, cannot remove. jun 03, 2014 12:10:01 AM com.jme3.bullet.PhysicsSpace removeRigidBody ADVERTENCIA: RigidBody com.jme3.bullet.control.RigidBodyControl0329a3abd does not exist in Physics Space, cannot remove jun 03, 2014 12:10:01 AM com.jme3.bullet.PhysicsSpace removeRigidBody ADVERTENCIA: RigidBody com.jme3.bullet.control.RigidBodyControl@44cb92e2 does not exist in Physics Space, cannot remove jun 03, 2014 12:10:01 AM com.jme3.bullet.PhysicsSpace removeRigidBody ADVERTENCIA: RigidBody com.jme3.bullet.control.RigidBodyControl@1ccf5036 does not exist in Physics Space, cannot remove. jun 03, 2014 12:10:01 AM com.jme3.bullet.PhysicsSpace removeRigidBody ADVERTENCIA: RigidBody com.jme3.bullet.control.RigidBodyControl@273deb57 does not exist in Physics Space, cannot remove. jun 03, 2014 12:10:01 AM com.jme3.bullet.PhysicsSpace removeRigidBody ADVERTENCIA: RigidBody com. ime3.bullet.control.RigidBodyControl0449172df does not exist in Physics Space, cannot remove jun 03, 2014 12:10:01 AM com.jme3.bullet.PhysicsSpace removeRigidBody ADVERTENCIA: RigidBody com.jme3.bullet.control.RigidBodyControl@5c55b42d does not exist in Physics Space, cannot remove. jun 03, 2014 12:10:01 AM com.jme3.bullet.PhysicsSpace removeRigidBody ADVERTENCIA: RigidBody com.jme3.bullet.control.RigidBodyControl@3afd1171 does not exist in Physics Space, cannot remove. ServerManager Stopped!! pablo@pablo-Latitude-E6540:-/ucm/sociAAL/code/phat-projects/paams-filters\$ ant edit Buildfile: /home/pablo/ucm/sociAAL/code/phat-projects/paams-filters/build.xml init: getclasspathfrommaven: generateclasspathfrommaven: edit [java] INGENIAS Development Kit (C) 2012 Jorge Gomez [java] This program comes with ABSOLUTELY NO WARRANTY; for details check www.gnu.org/copylef /gpl.html. [java] This is free software, and you are welcome to redistribute it under certain condition for details check www.gnu.org/copyleft/gpl.html. [java] SwixML 1.2 (#140) [java] specification.xml BUTED SUCCESSEU Total time: 2 minutes 22 seconds pablo@pablo-Latitude-E6540:~/ucm/sociAAL/code/phat-projects/paams-filters\$ ant edit

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Conclusions

- A Maven based model driven development is possible
 - Ensures stabitily and eases the software reuse
 - Homogenizes the development
 - regardless the technology, it is always mvn compile && mvn install
- If support tools are slowing you down, perhaps they are not as supportive as you thought
 - There are alternatives to EMF
 - Choosing them is not a limiting choice: you can choose again
- SociAALML is a complex code generation case and it is expected to keep on evolving
 - INGENIAS is even more complex

